

Tree-Traversal Orientation Analysis

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Overview

A compiler-based analysis to determine the predominant orientation of traversal of trees.

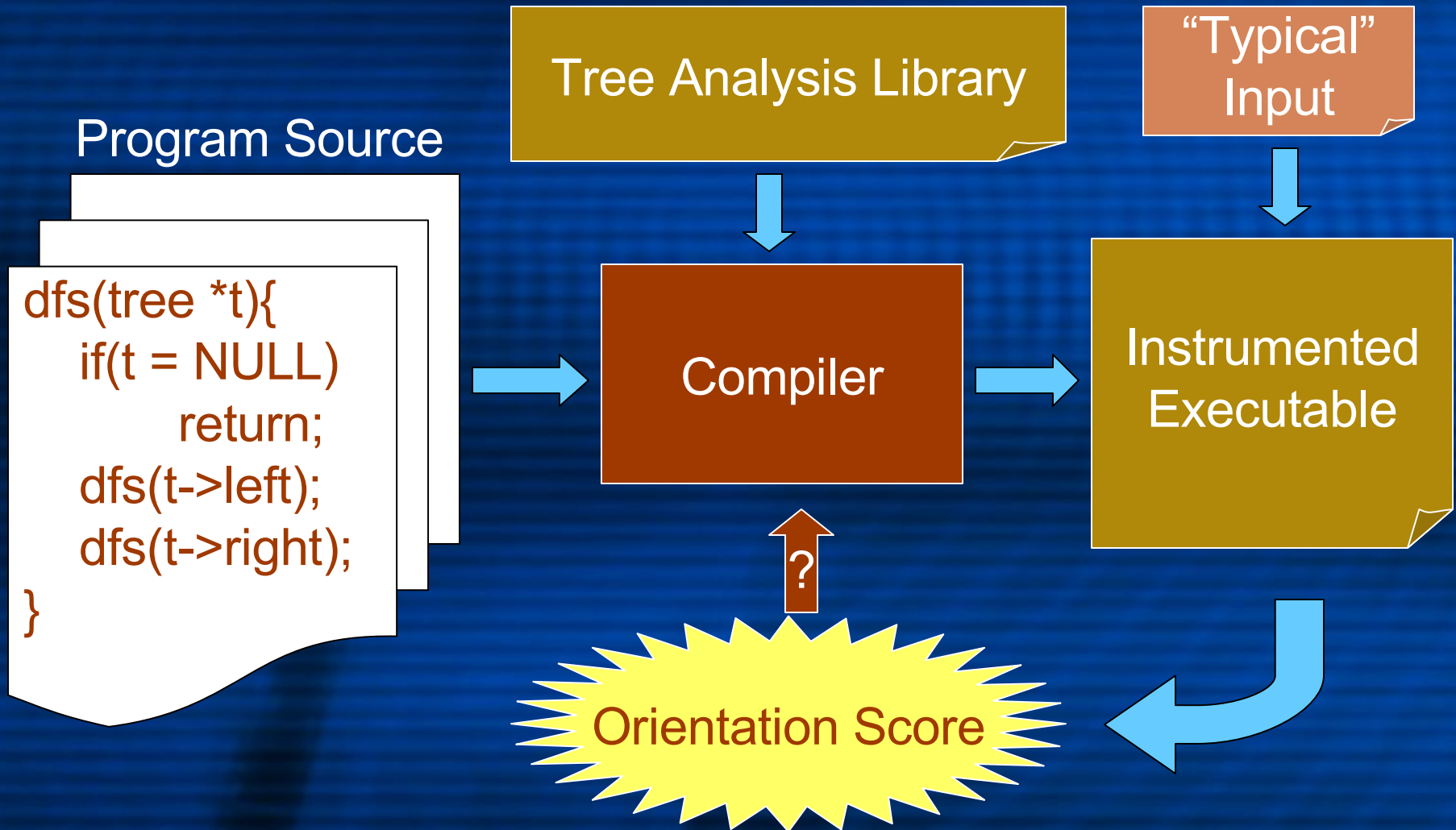
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Overview

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Overview



Tree-Traversal Orientation Analysis



Returns an *orientation score* $\in [-1, 1]$

1 is depth-first traversal

-1 is breadth first traversal

0 is an unknown traversal

Calculating the Orientation Score

Every memory access to a tree is classified as:

Depth-First

Breadth-First

Both

Neither

The *orientation score* of each tree is calculated as:

$$\frac{\text{num_depth} - \text{num_breadth}}{\text{num_accesses}} \quad [-1,1]$$

Calculating the Orientation Score

A linked-list access could be classified as both Breadth- and Depth-First.

In this analysis a memory access to a 1-arity tree is classified as Depth-First.

An alternative is to provide a three-dimensional score that also classifies linked-list traversal.

Determining if an Access is Depth-First

The TAL maintains a stack of *choice-points* for each tree.

Each choice-point consists of:

1. the address of a node, t , in the tree,
2. all n children of t , $c_1 \dots c_n$, with a boolean representing if they have been visited, and
3. a boolean value representing if the node has been visited

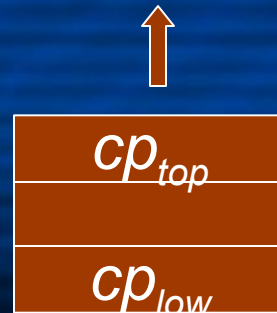
Determining if a Access is Depth-First

cp_{top} : the address of the choice point on top of the stack;

t : the address of the tree node been referenced now;

cp_{low} : the address of a choice point below

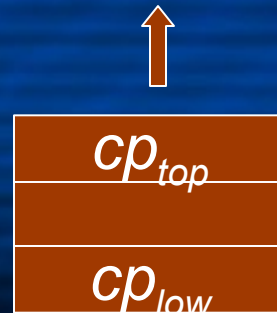
cp_{top} in the stack;



Determining if a Access is Depth-First

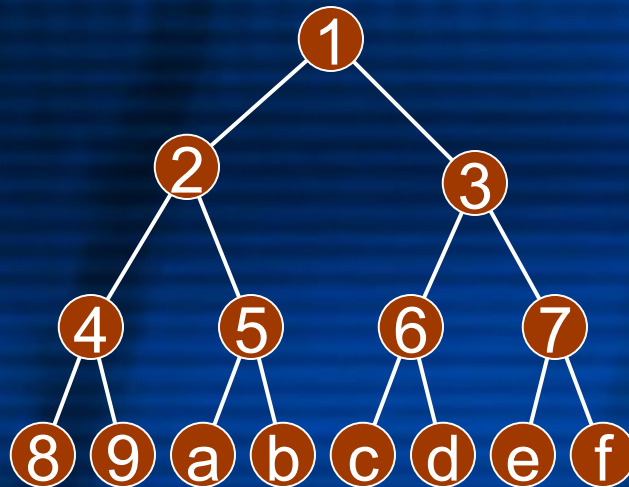
An access to tree node t is classified as depth-first if and only if:

- | cp_{top} is equal to t ; OR
- | A child c_i of cp_{top} is equal to t ; OR
- | There exists a lower choice point in the stack cp_{low} such that cp_{low} or a child of cp_{low} is equal t AND all of the choice-points on the stack above cp_{low} have been visited.



Determining if a Access is Depth-First

Every time a node is visited, a choice-point for that node is pushed onto the stack.

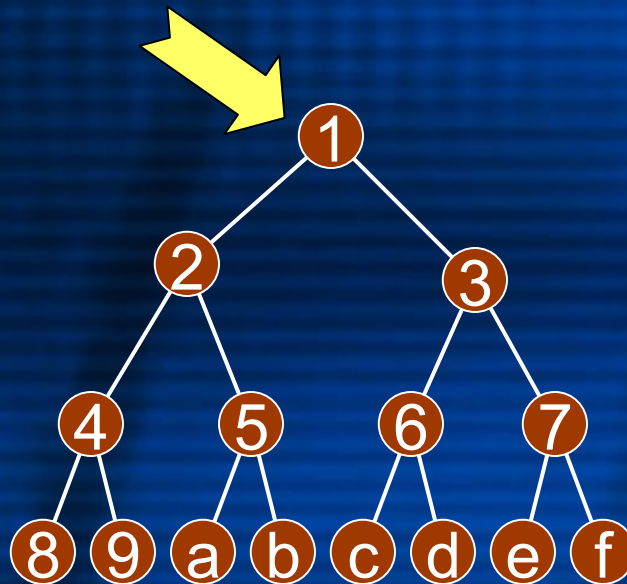


...

Determining if a Access is Depth-First

Every time a node is visited, a choice-point for that node is pushed onto the stack.

t = 1



1 (2,3) C_{top}

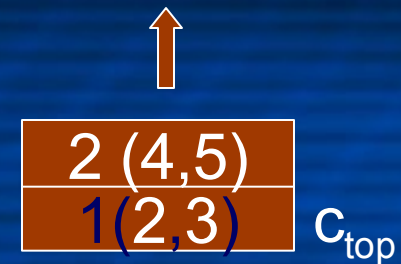
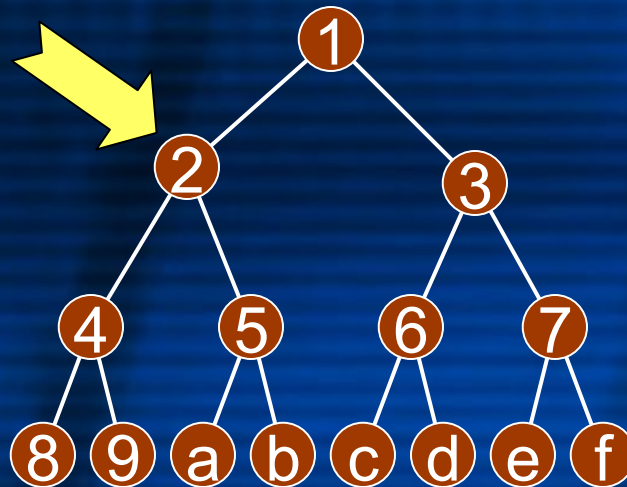
node (c1,c2)

...

Determining if a Access is Depth-First

Condition 2: $t = c_1 \rightarrow 2$ is DFS

$t = 2$



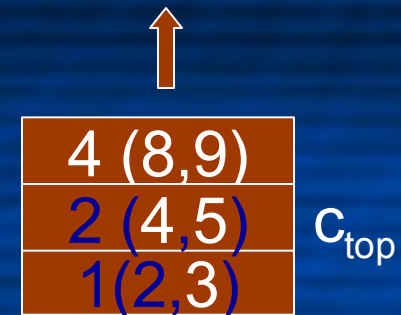
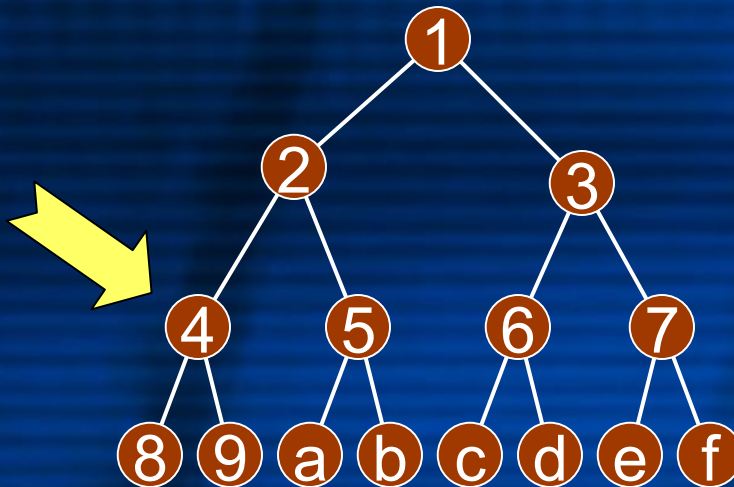
...

Dark color means visited

Determining if a Access is Depth-First

Condition 2: $t = c_1 \rightarrow 4$ is DFS

$t = 4$

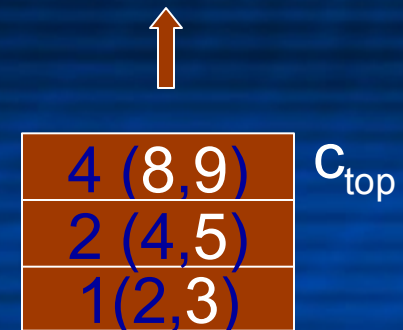
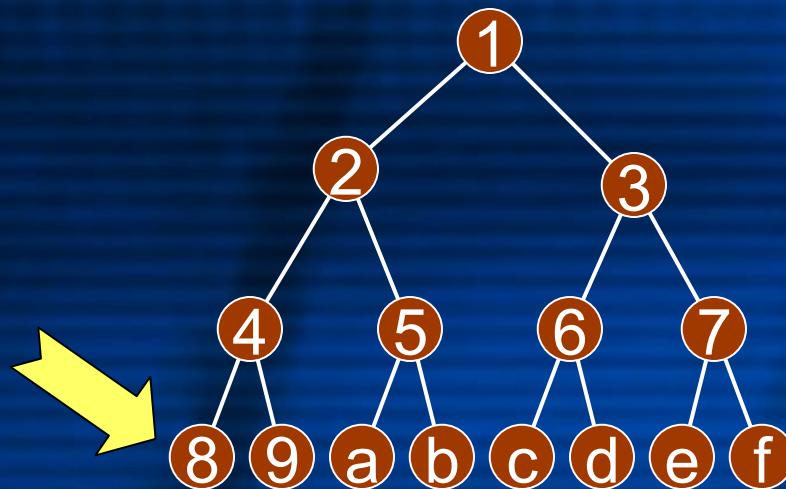


...

Determining if a Access is Depth-First

Condition 2: $t = c_1 \rightarrow 8$ is DFS

$t = 8$

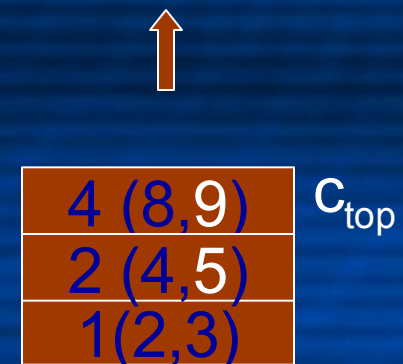
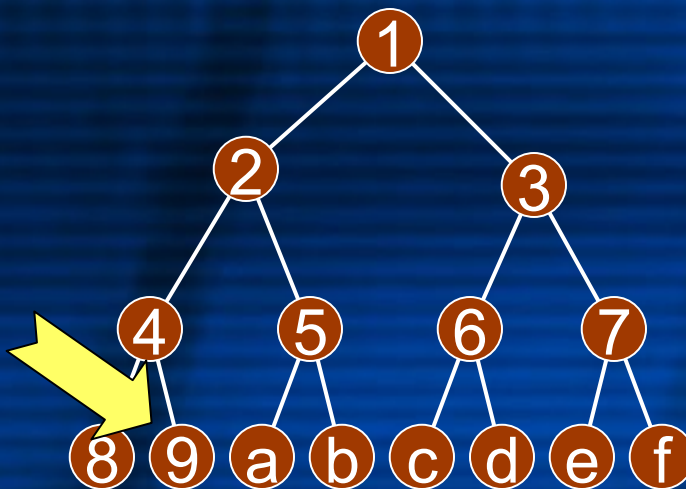


Note: Children of 8 are null thus 8 is not a choice point.

Determining if a Access is Depth-First

Condition 2: $t = c_2 \rightarrow 9$ is DFS

$t = 9$

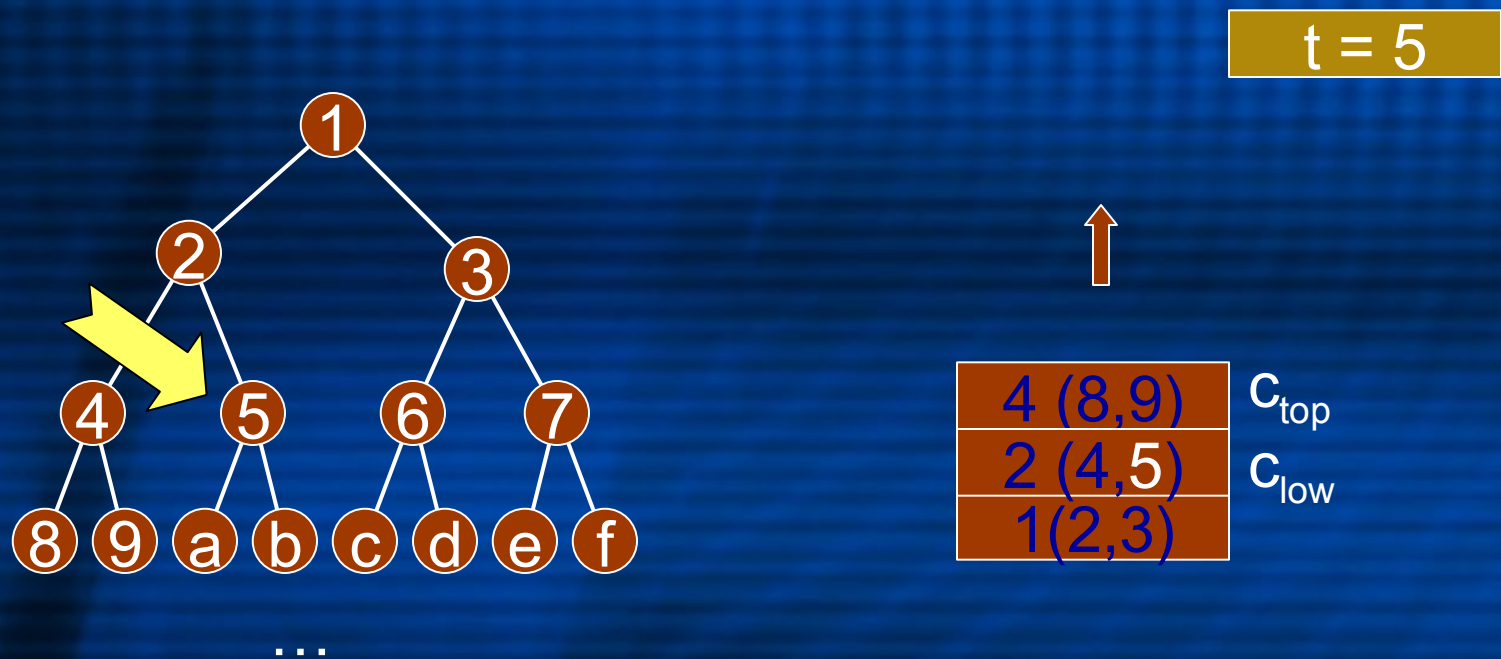


Note: Children of 9 are null thus 9 is not a choice point.

Determining if a Access is Depth-First

Condition 3: $t = c_{low} \cdot c_2 \rightarrow 5$ is DFS

Pop everything above c_{low}

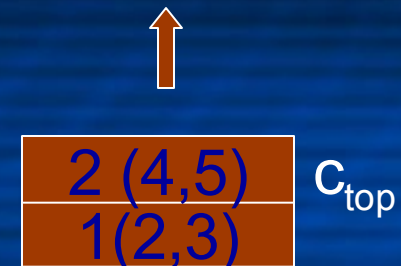
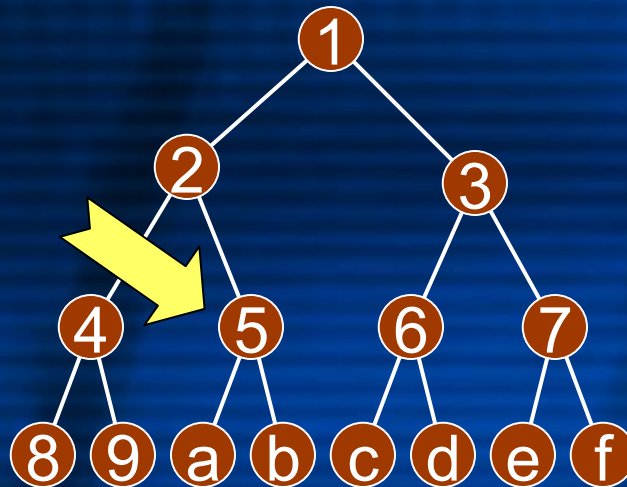


Determining if a Access is Depth-First

Condition 3: $t = c_{low} \cdot c_2 \rightarrow 5$ is DFS

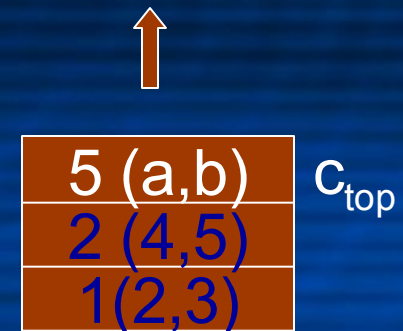
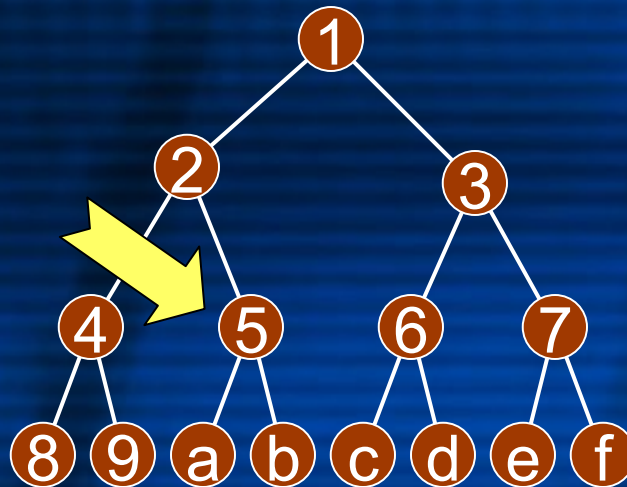
Pop everything above c_{low}

$t = 5$



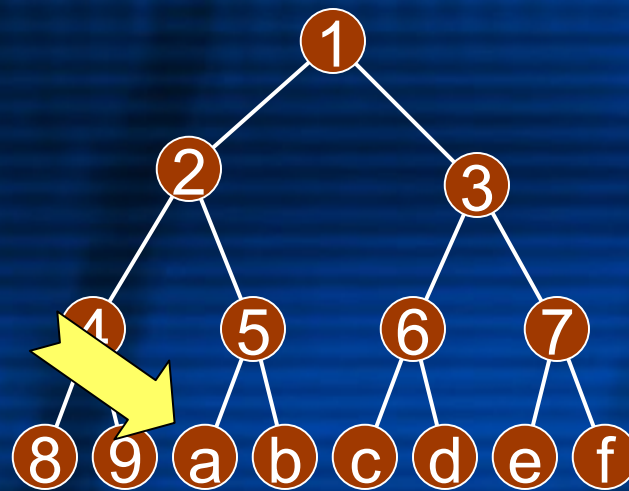
Determining if a Access is Depth-First

t = 5

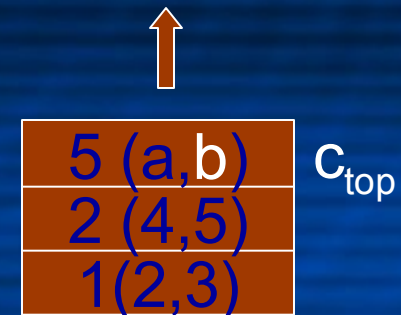


Determining if a Access is Depth-First

Condition 2: $t = c_1 \rightarrow a$ is DFS

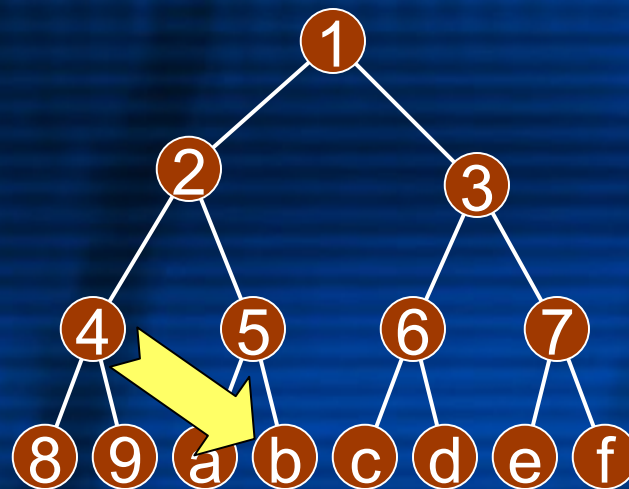


$t = a$

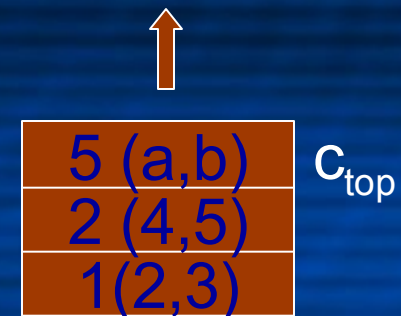


Determining if a Access is Depth-First

Condition 2: $t = c_2 \rightarrow b$ is DFS



$t = b$

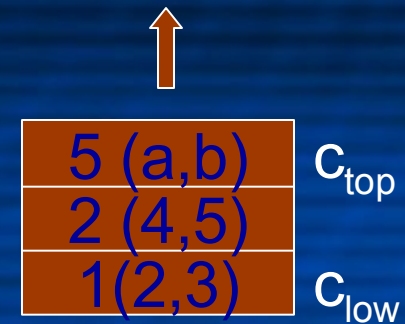
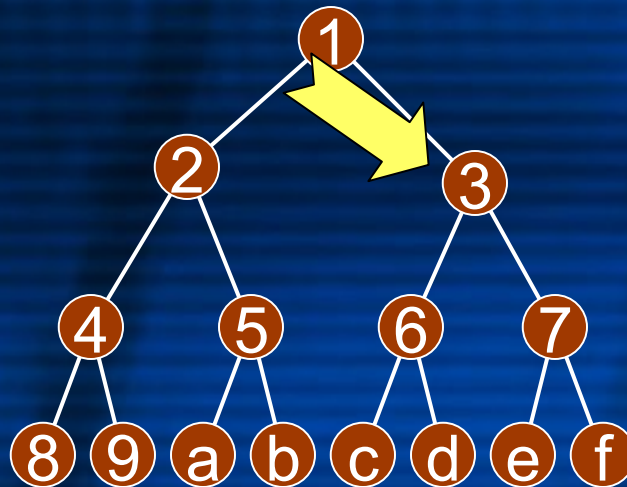


Determining if a Access is Depth-First

Condition 3: $t = c_{low} \cdot c_2 \rightarrow b$ is DFS

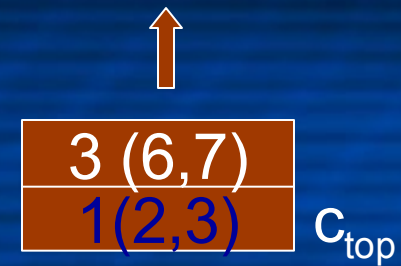
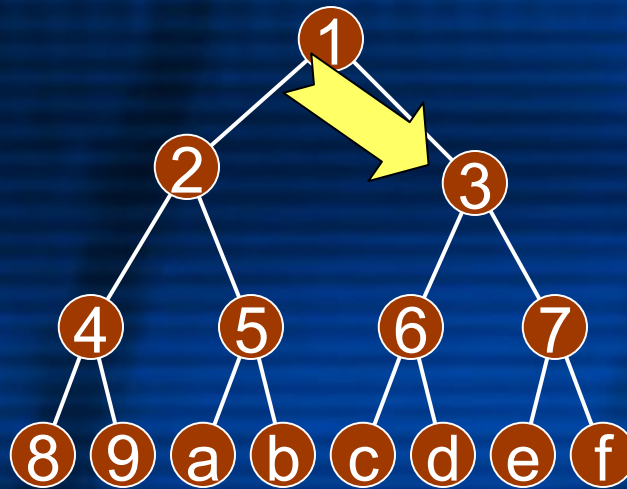
Pop everything above c_{low}

$t = 3$



Determining if a Access is Depth-First

t = 3



Determining if a Access is Breadth-First

The TAL maintains an *open* and *next list* for each tree.

They are stored as double-ended bit-vectors.

If an access is found in the open list it is classified as Breadth-First.

| | | | | | | | | | | | | | | | |
|------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| Open | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | a | b | c | d | e | f |
| Next | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | a | b | c | d | e | f |

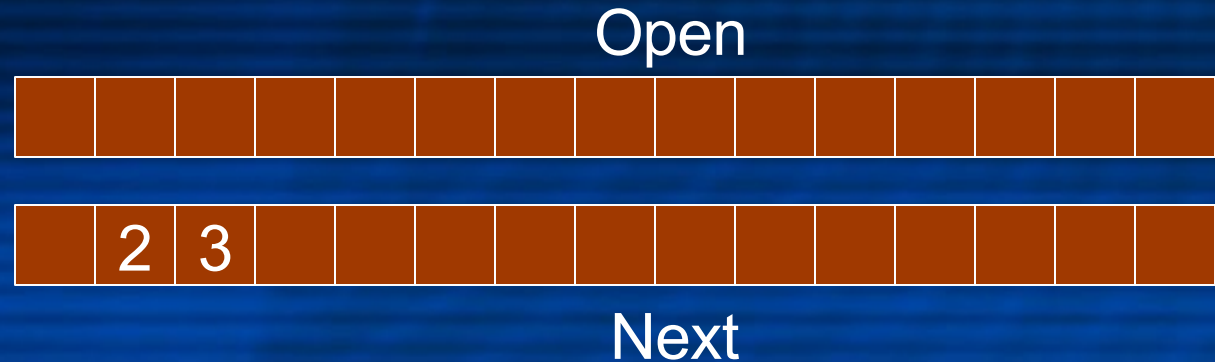
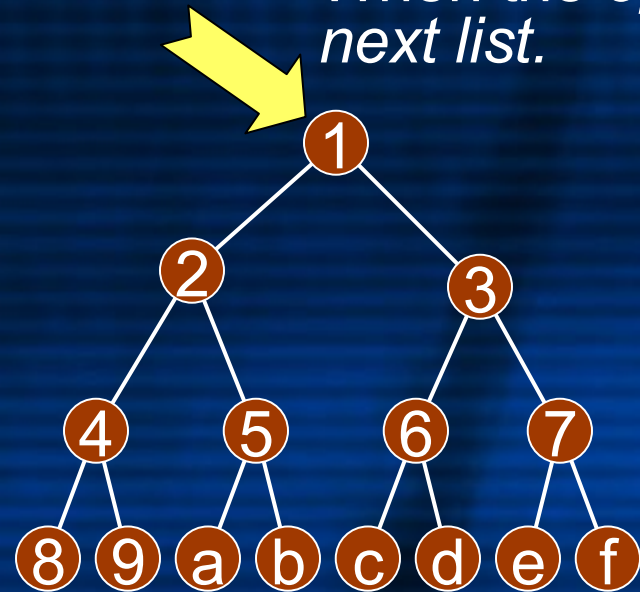
Determining if a Access is Breadth-First

When tree node t is accessed:

The children of t are added to the *next list*.

If t is in the open list it is removed from the open list and the access is classified as breadth first.

When the *open list* is empty it is swapped with the *next list*.



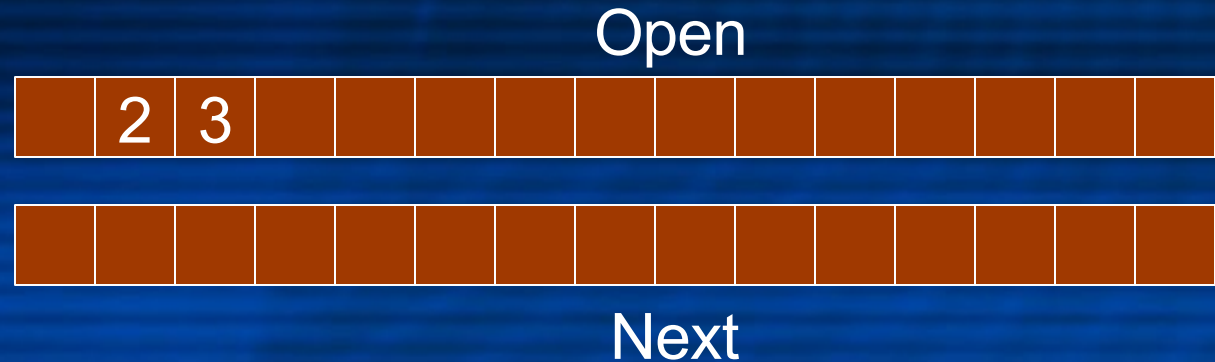
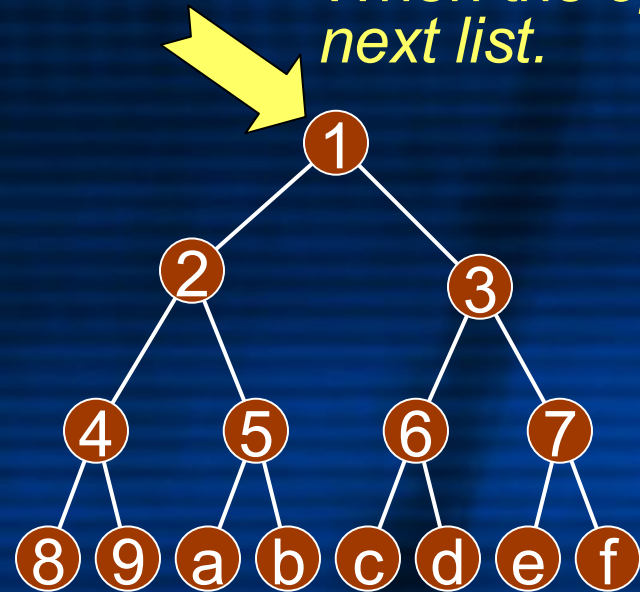
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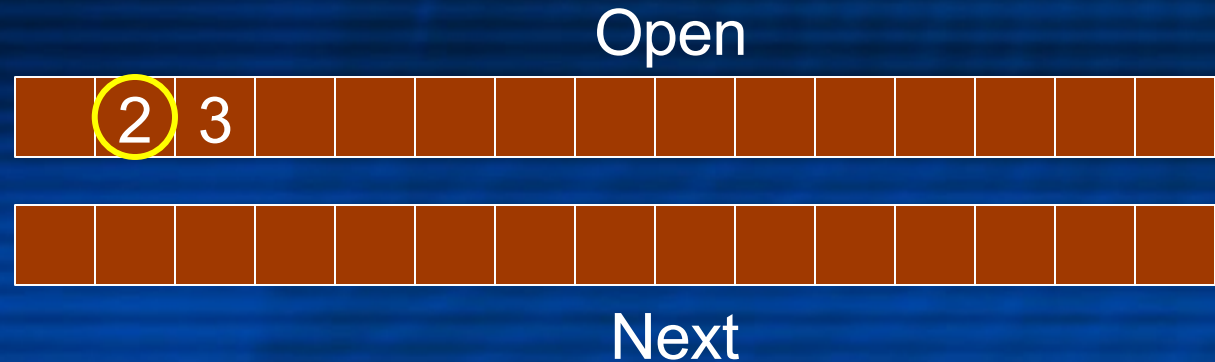
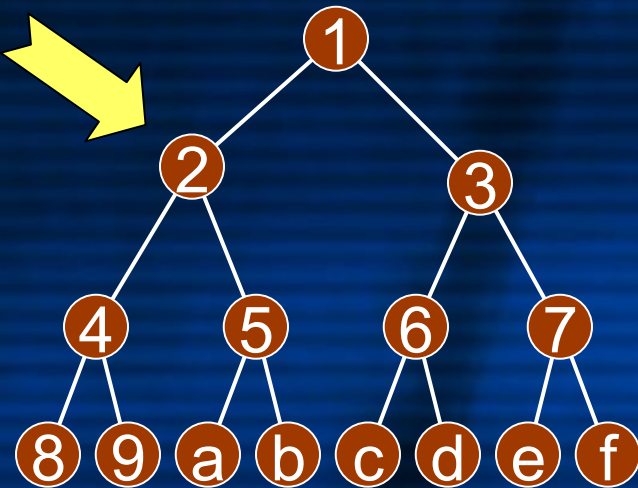
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Access is classified as Breadth-First

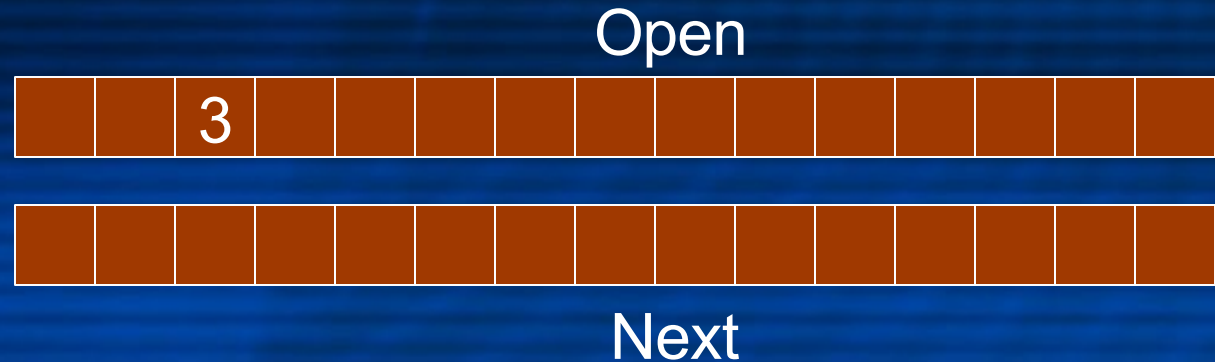
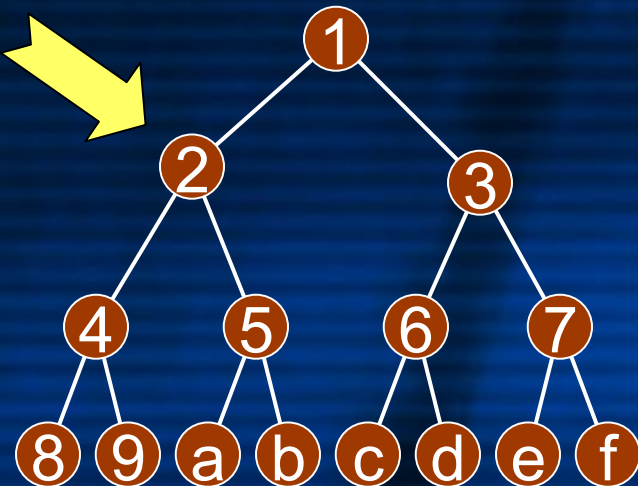
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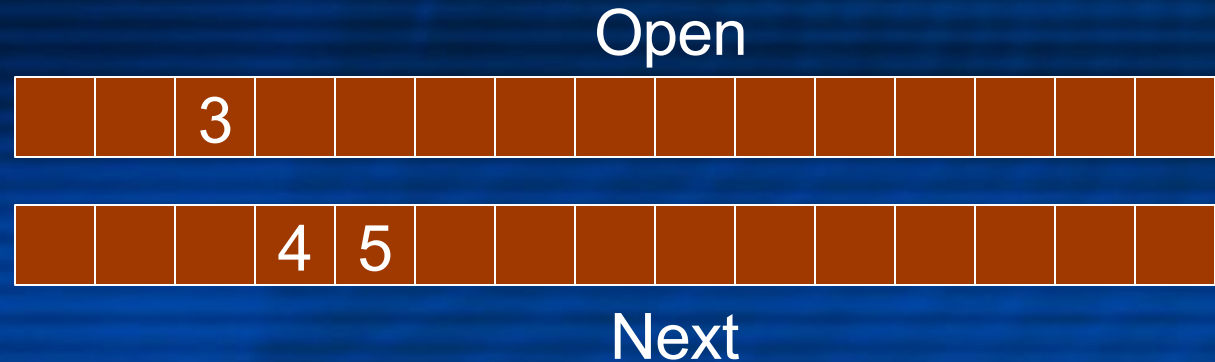
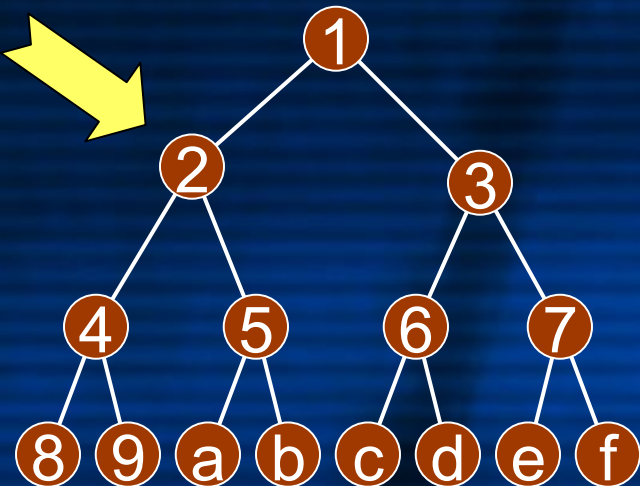
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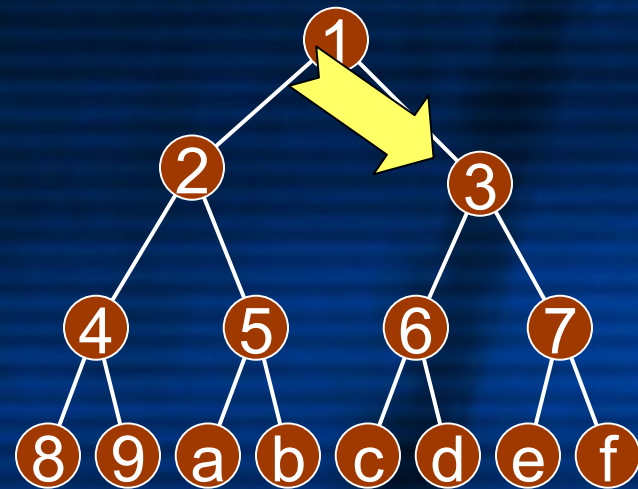
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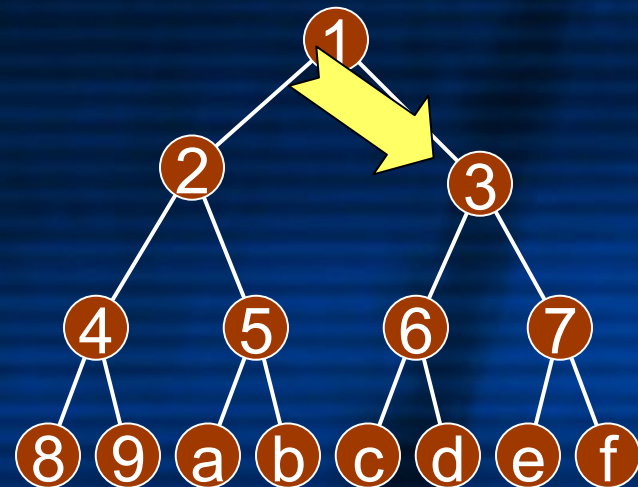
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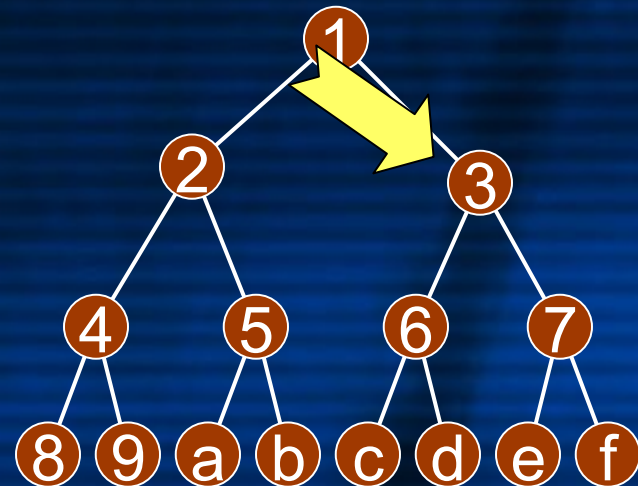
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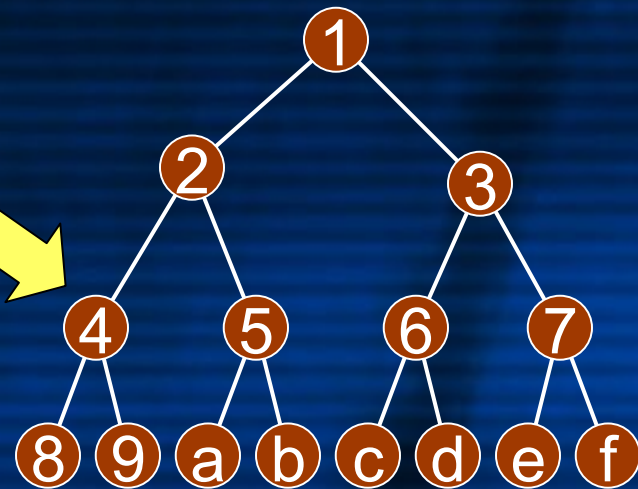
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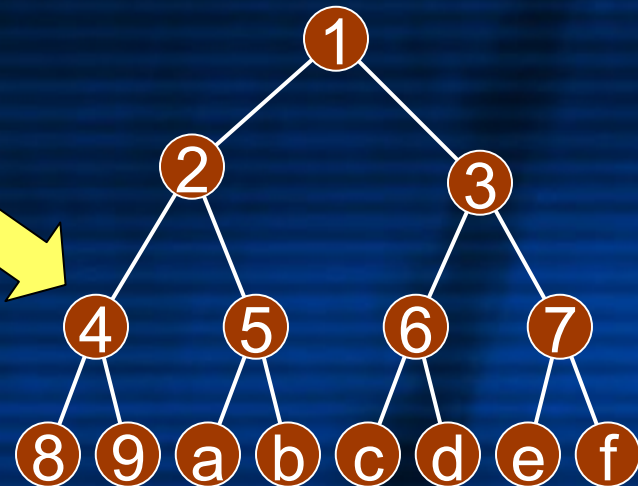
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Implementation

Built in the Open Research Compiler (ORC)

Operates on the WHIRL (Winning Hierarchical Intermediate Representation Language) IR.

Analysis requires Interprocedural Analysis (IPA).

Automatically identifies link-based tree data structures using Ghiya and Hendren's analysis [2] or programmer annotations.

Instrumentation can be inserted into each procedure without IPA.

Implementation

Calls our Tree Analysis Library (TAL)

```
register_tree_access_with_children()
```

Takes Parameters:

```
void *addr_deref  
int tree_id  
int num_children  
void *child_addr, ...
```

Implementation

Analysis is safe and will not cause a correct program to fail.

Replace calls to malloc/calloc/realloc with TALs wrapper functions.

If memory allocation fails, the analysis is abandoned and the memory used by the analysis is freed.

Memory address are calculated and accessed for the instrumentation in locations that are safe.

i.e. Will not dereference null pointers

```
if( tree != NULL && tree->data == 1)
```

How do we identify tree references?

Example Code:

```
/* inorder tree traversal */
void inorder_traverse_tree(struct tn *tree_ptr)
{

    if(tree_ptr == NULL)
        return;

    inorder_traverse_tree(tree_ptr->left);
    tree_ptr->data++;
    inorder_traverse_tree(tree_ptr->right);

}
```

```

LOC 1 94 void inorder_traverse_tree(struct tn *tree_ptr)
LOC 1 95 {
FUNC_ENTRY <1,25,inorder_traverse_tree>
IDNAME 0 <2,1,tree_ptr>
BODY
LOC 1 96  if(tree_ptr == NULL)
IF
  U8U8LDID 0 <2,1,tree_ptr> T<32,anon_ptr.,8>
  U8INTCONST 0 (0x0)
  I4U8EQ
THEN
  BLOCK
LOC 1 97  return;
RETURN
END_BLOCK
ELSE
LOC 1 96  BLOCK
END_BLOCK
END_IF
LOC 1 100
LOC 1 101  inorder_traverse_tree(tree_ptr->left);
  U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>
  U8U8ILOAD 8 T<30,tn,8> T<31,anon_ptr.,8>
    <field_id:2>
  U8PARM 2 T<31,anon_ptr.,8> # by_value
VCALL 126 <1,25,inorder_traverse_tree> # flags 0x7e

```

```

void inorder_traverse_tree(struct tn
 *tree_ptr)
{ if(tree_ptr == NULL)
  return;
  inorder_traverse_tree(tree_ptr-
>left);
  tree_ptr->data++;
  inorder_traverse_tree(tree_ptr-
>right);
}

```

```

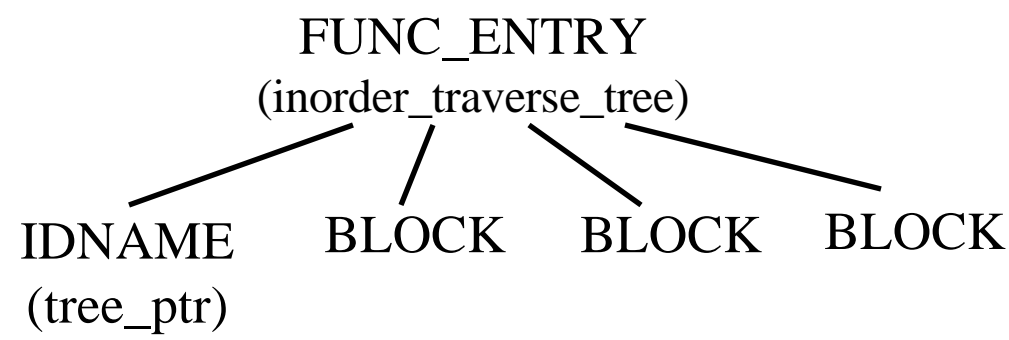
LOC 1 102  tree_ptr->data++;
  U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>
  I4I4ILOAD 0 T<30,tn,8> T<31,anon_ptr.,8> <field_id:1>
  I4INTCONST 1 (0x1)
  I4ADD
  U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>
  I4ISTORE 0 T<31,anon_ptr.,8> <field_id:1>
LOC 1 103  inorder_traverse_tree(tree_ptr->right);
  U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>
  U8U8ILOAD 16 T<30,tn,8> T<31,anon_ptr.,8> <field_id:3>
  U8PARM 2 T<31,anon_ptr.,8> # by_value
VCALL 126 <1,25,inorder_traverse_tree> # flags 0x7e
RETURN
END_BLOCK

```

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LOC 1 95 {
FUNC_ENTRY <1,25,inorder_traverse_tree>
IDNAME 0 <2,1,tree_ptr>
BODY
BLOCK
END_BLOCK
BLOCK
END_BLOCK
BLOCK

U8U8LDID 0 <2,1,tree_ptr> T<32,anon_ptr.,8>
U8INTCONST 0 (0x0)
I4U8EQ
THEN
BLOCK
LOC 1 97 return;
RETURN
END_BLOCK
ELSE
LOC 1 96
BLOCK
END_BLOCK
END_IF

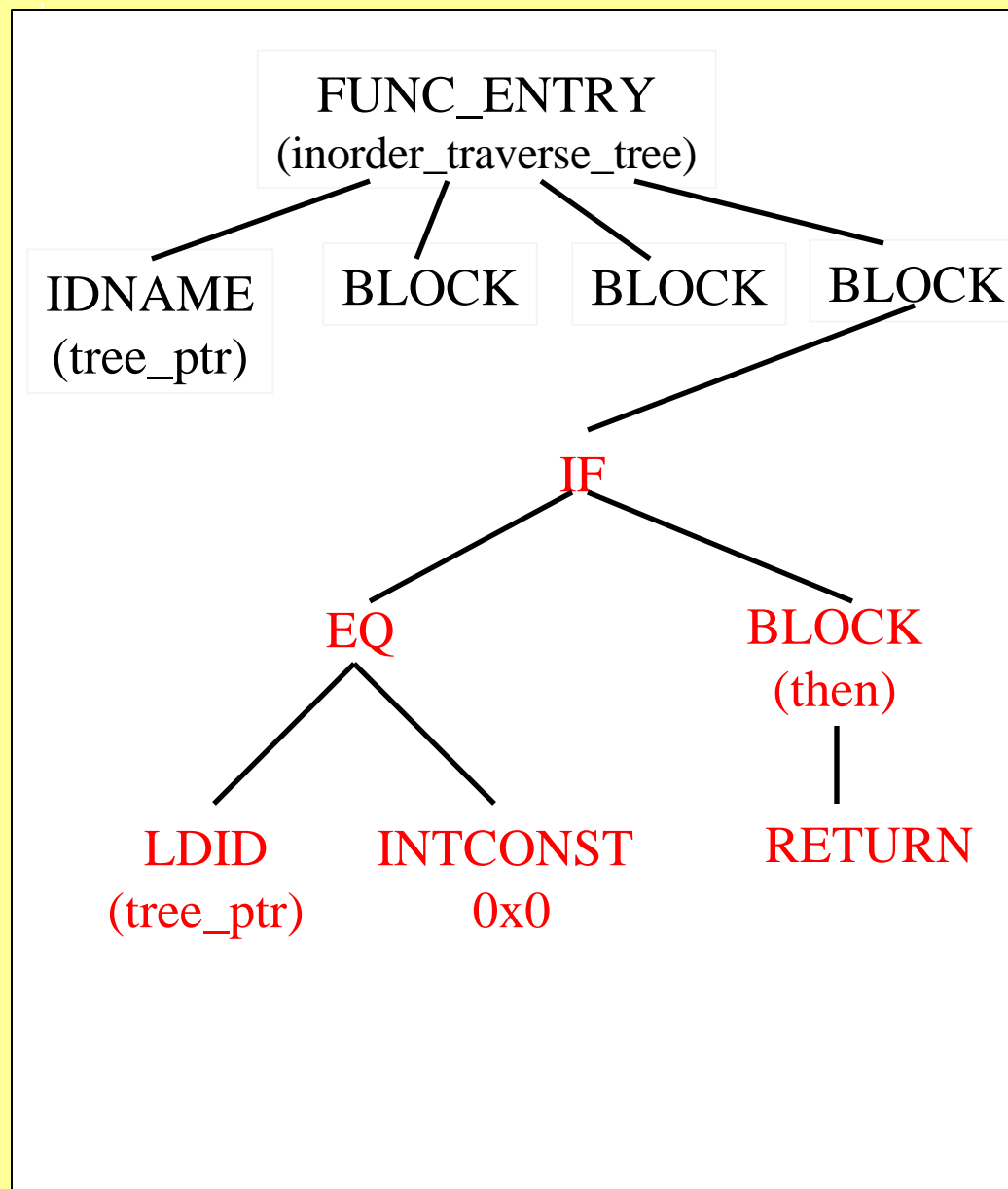


0x7e
RETURN
END_BLOCK

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LOC 1 94 void inorder_traverse_tree(struct tn *tree_ptr)
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FUNC_ENTRY <1,25,inorder_traverse_tree>
IDNAME 0 <2,1,tree_ptr>
BODY
BLOCK
END_BLOCK
BLOCK
END_BLOCK
BLOCK
PRAGMA 0 120 <null-st> 0 (0x0) # PREAMBLE_END
LOC 1 96 if(tree_ptr == NULL)
IF
  U8U8LDID 0 <2,1,tree_ptr> T<32,anon_ptr.,8>
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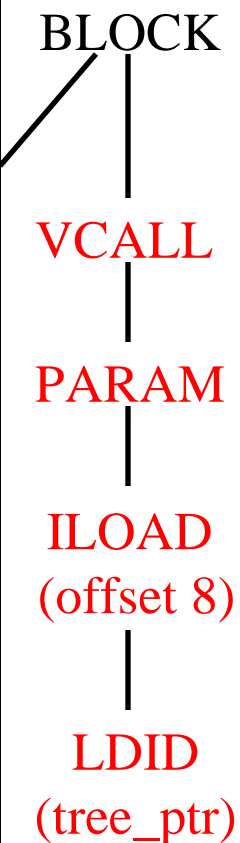
```



```

0x7e
RETURN
END_BLOCK

```



LOC 1 100

LOC 1 101 `inorder_traverse_tree(tree_ptr->left);`

U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>

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U8PARAM 2 T<31,anon_ptr.,8> # by_value

VCALL 126 <1,25,inorder_traverse_tree> # flags 0x7e
0x7eLOC 1 102 `tree_ptr->data++;`

U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>

I4ILOAD 0 T<30,tn,8> T<31,anon_ptr.,8>

<field_id:1>

I4INTCONST 1 (0x1)

I4ADD

U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>

I4ISTORE 0 T<31,anon_ptr.,8> <field_id:1>

LOC 1 103 `inorder_traverse_tree(tree_ptr->right);`

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U8U8ILOAD 16 T<30,tn,8> T<31,anon_ptr.,8>

<field_id:3>

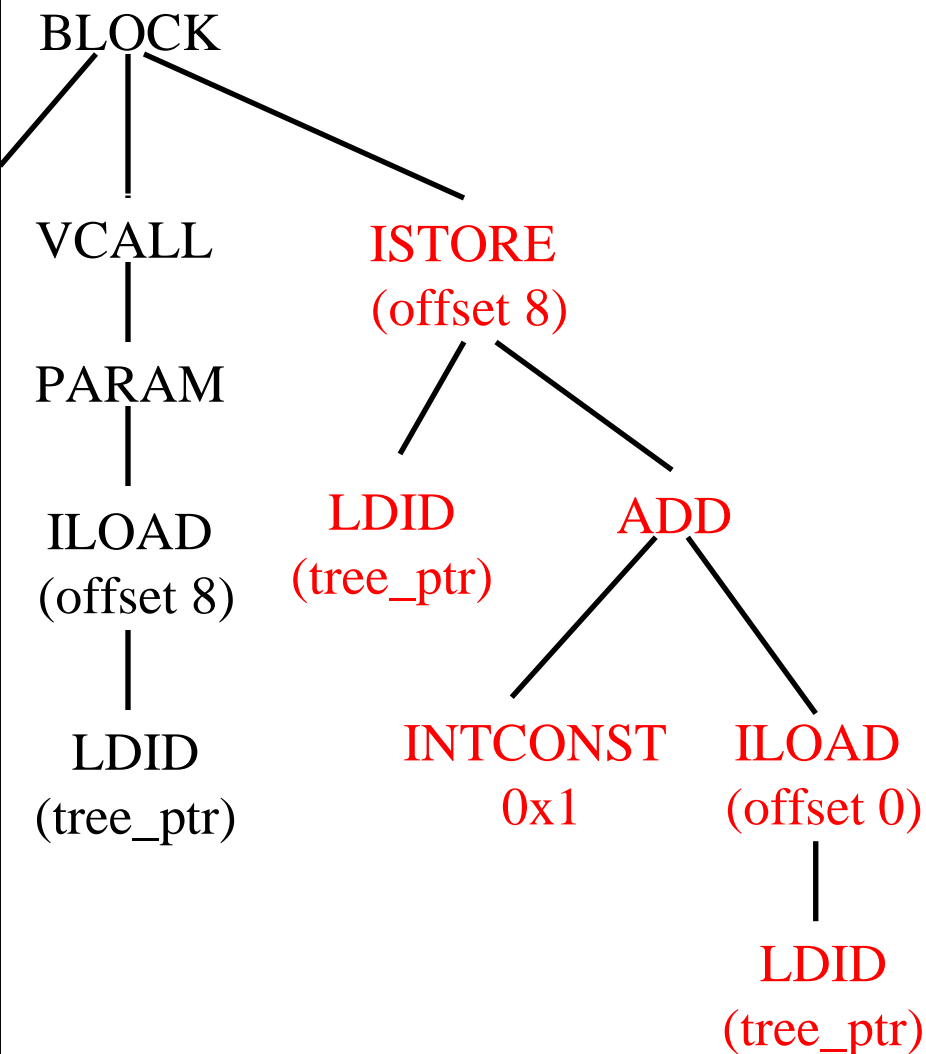
U8PARAM 2 T<31,anon_ptr.,8> # by_value

VCALL 126 <1,25,inorder_traverse_tree> # flags
0x7e

RETURN

END_BLOCK

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U8U8ILOAD 8 T<30,tn,8> T<31,anon_ptr.,8>
<field_id:2>

U8PARAM 2 T<31,anon_ptr.,8> # by_value

VCALL 126 <1.25.inorder_traverse_tree> # flags

LOC 1 102 tree_ptr->data++;

U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>

I4I4ILOAD 0 T<30,tn,8> T<31,anon_ptr.,8> 8>
<field_id:1>

I4INTCONST 1 (0x1)

I4ADD

U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>

I4ISTORE 0 T<31,anon_ptr.,8> <field_id:1>

I4ISTORE 0 T<31,anon_ptr.,8> <field_id:1>

LOC 1 103 inorder_traverse_tree(tree_ptr->right);

U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>

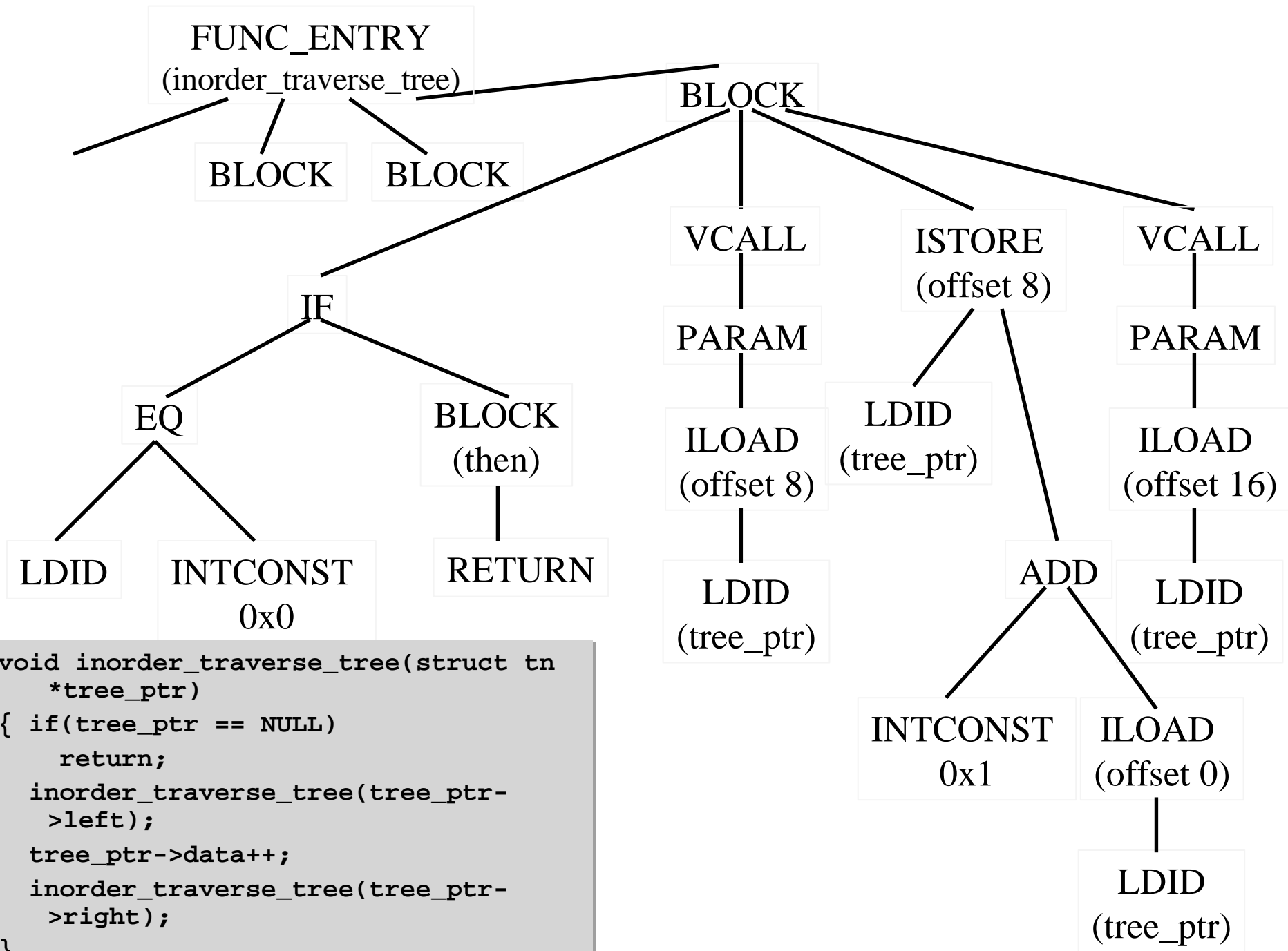
U8U8ILOAD 16 T<30,tn,8> T<31,anon_ptr.,8>
<field_id:3>

U8PARAM 2 T<31,anon_ptr.,8> # by_value

VCALL 126 <1,25,inorder_traverse_tree> # flags
0x7e

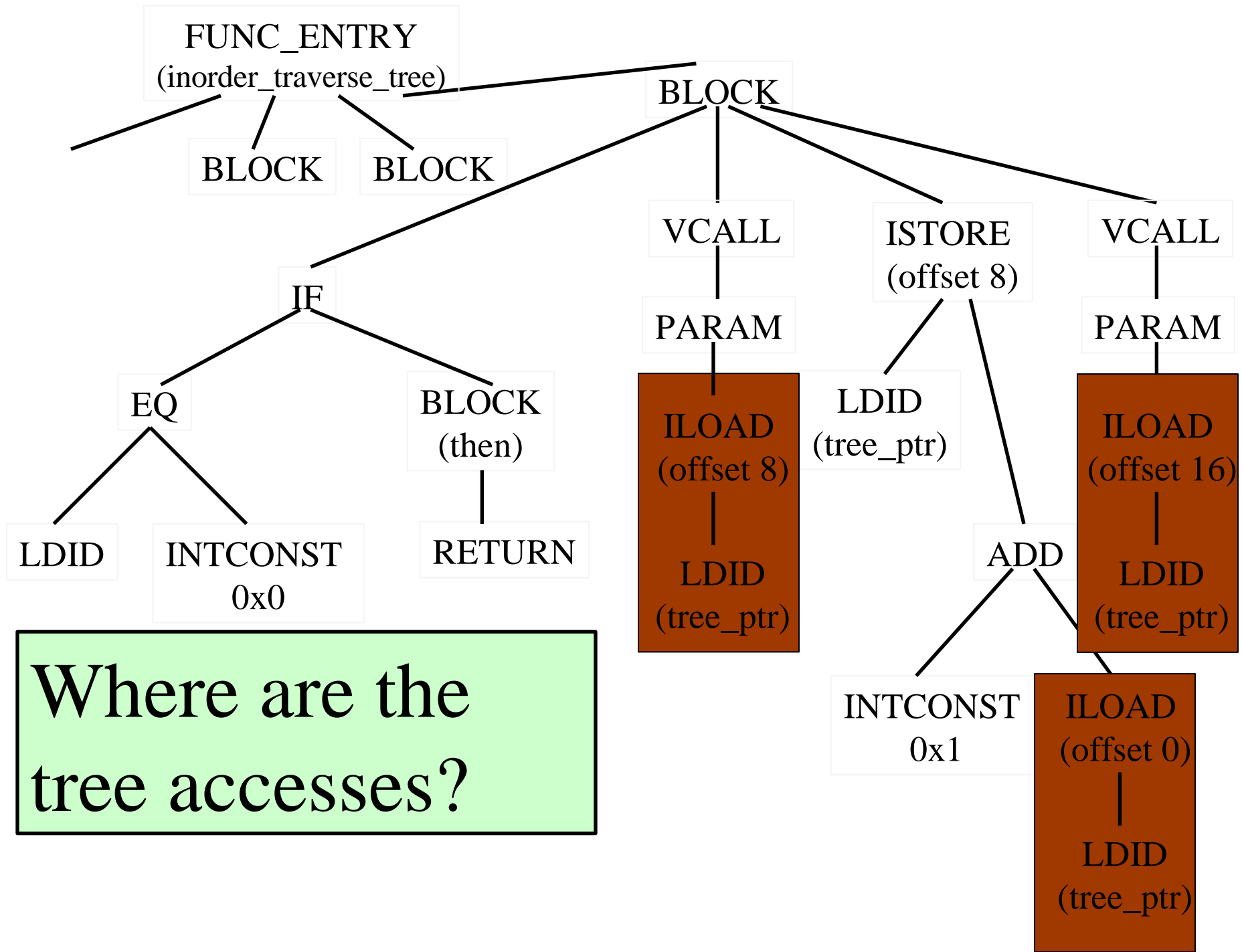
RETURN

END_BLOCK

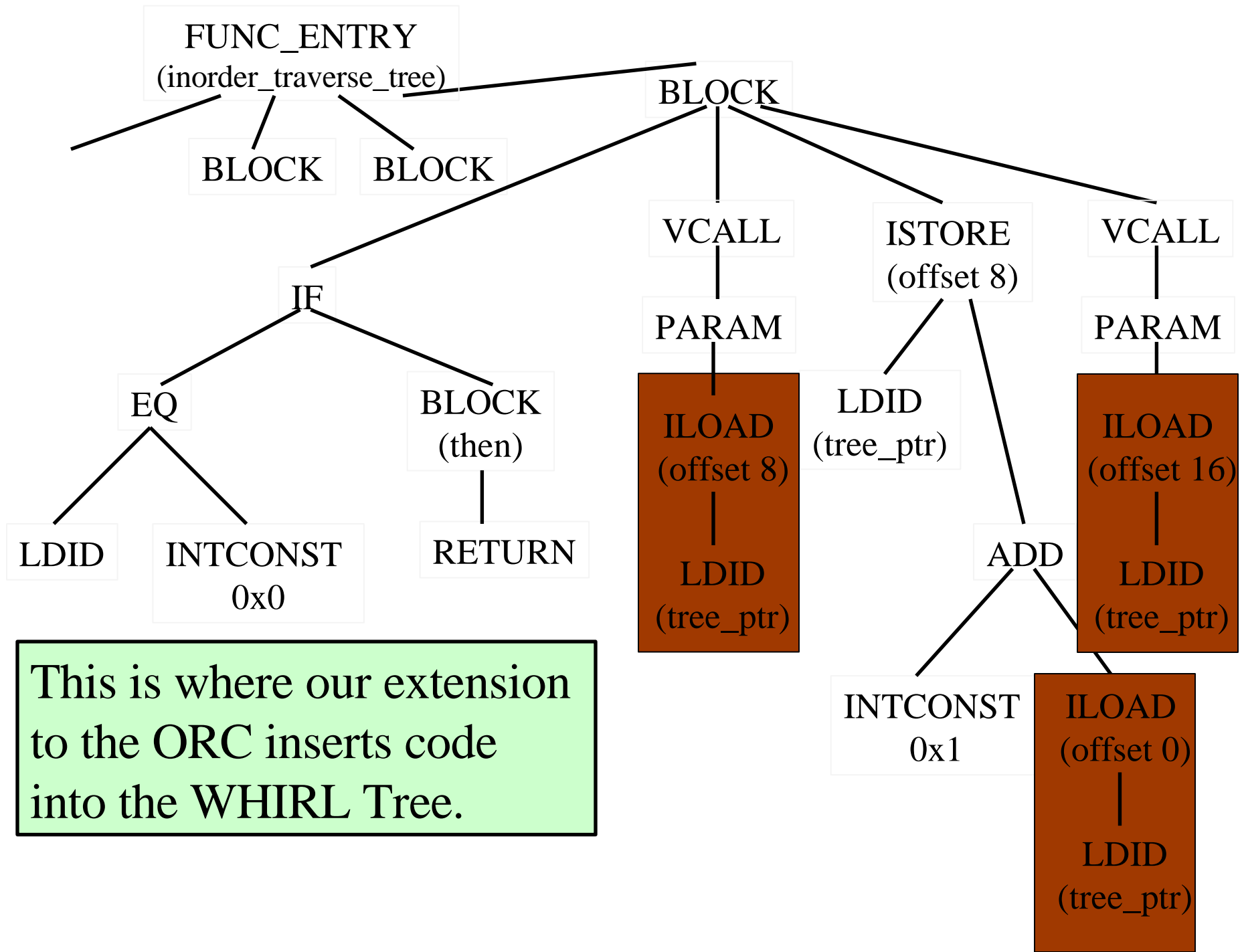


```

void inorder_traverse_tree(struct tn
    *tree_ptr)
{ if(tree_ptr == NULL)
    return;
  inorder_traverse_tree(tree_ptr-
    >left);
  tree_ptr->data++;
  inorder_traverse_tree(tree_ptr-
    >right);
}
  
```



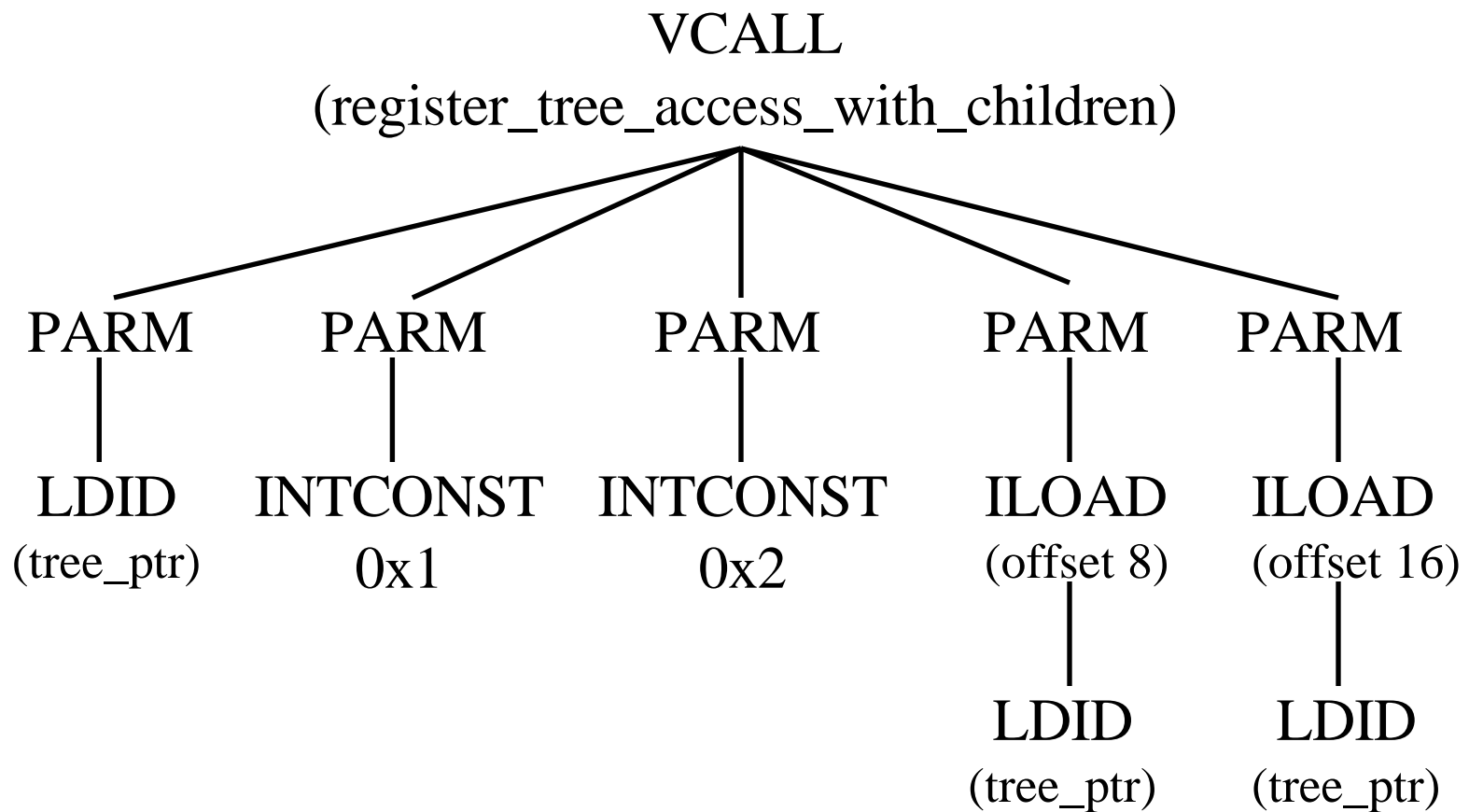
Where are the tree accesses?



The Nodes we Insert Into WHIRL

```
U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>
  U8PARAM 2 T<31,anon_ptr.,8> # by_value
U4INTCONST 1 (0x1)
  U4PARAM 2 T<8,.predef_U4,4> # by_value
  U4INTCONST 2 (0x2)
  U4PARAM 2 T<8,.predef_U4,4> # by_value
    U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>
    U8U8ILOAD 8 T<31,anon_ptr.,8> T<34,anon_ptr.,8>
    U8PARAM 2 T<31,anon_ptr.,8> # by_value
    U8U8LDID 0 <2,1,tree_ptr> T<31,anon_ptr.,8>
    U8U8ILOAD 16 T<31,anon_ptr.,8> T<34,anon_ptr.,8>
    U8PARAM 2 T<31,anon_ptr.,8> # by_value
VCALL 126 <1,21,register_access_with_children> # flags 0x7e
```

The Nodes we Insert Into WHIRL



Experimental Setup

Open Research Compiler v2.1

Optimization level -O3

1.3 GHz Itanium2

1 GB of RAM

Synthetic Benchmarks

RandomDepth: DFS traversal of binary tree, children visited in random order;

BreadthFirst: BFS on binary tree;

DepthBreadth: DFS followed by BFS on binary tree;

NonStandard: A traversal that is neither BFS nor DFS;

MultiDepth: Several DFSs: in-order, pre-order, and post-order;

BreadthSearch: Several BFS searches on a tree with random branching factor (2 to 6);

BinarySearch: Several searches in a binary tree.

Analysis Results

(Synthetic Benchmark)

| Benchmark | Orientation Score | |
|----------------|-------------------|--------------|
| | Expected | Experimental |
| Random Depth | 1.0 | 1.000000 |
| Breadth-First | -1.0 | -0.999992 |
| Depth-Breadth | 0.0 | 0.000000 |
| Non-Standard | 0.0 | 0.136381 |
| Multi Depth | 1.0 | 0.999974 |
| Breadth Search | -1.0 | -0.995669 |
| Binary Search | 1.0 | 0.941225 |

Analysis Results

(Olden Benchmark)

| Benchmark | Orientation Score | |
|-----------|-------------------|--------------|
| | Expected | Experimental |
| BH | 0.0 | 0.010266 |
| Bisort | 0.0 | -0.001014 |
| Health | 1.0 | 0.807330 |
| MST | Low positive | 0.335852 |
| Perimeter | Low positive | 0.195177 |
| Power | 1.0 | 0.991617 |
| Treeadd | 1.0 | 1.000000 |
| TSP | Low positive | 0.173267 |

Runtime Overhead

(Synthetic Benchmark)

| Benchmark | Runtime (s) | |
|------------------|--------------------|---------------------|
| | Original | Instrumented |
| Random Depth | 0.90 | 10.72 |
| Breadth-First | 1.09 | 1.81 |
| Depth-Breadth | 1.33 | 7.84 |
| Non-Standard | 0.36 | 2.68 |
| Multi Depth | 0.47 | 3.94 |
| Breadth Search | 0.36 | 1.83 |
| Binary Search | 0.20 | 2.75 |

Runtime Overhead

(Olden Benchmark)

| Benchmark | Runtime (s) | |
|------------------|--------------------|---------------------|
| | Original | Instrumented |
| BH | 0.45 | 6.88 |
| Bisort | 0.03 | 1.01 |
| Health | 0.05 | 12.06 |
| MST | 5.71 | 11.42 |
| Perimeter | 0.02 | 1.55 |
| Power | 1.35 | 1.60 |
| Treeadd | 0.13 | 6.35 |
| TSP | 0.01 | 1.40 |

Memory Overhead

(Synthetic Benchmark)

| Benchmark | Memory Usage (kbytes) | |
|----------------|-----------------------|--------------|
| | Original | Instrumented |
| Random Depth | 854 976 | 855 040 |
| Breadth-First | 424 928 | 441 328 |
| Depth-Breadth | 220 112 | 252 896 |
| Non-Standard | 420 800 | 420 912 |
| Multi Depth | 529 344 | 652 288 |
| Breadth Search | 30 192 | 47 408 |
| Binary Search | 224 192 | 224 320 |

Memory Overhead

(Olden Benchmark)

| Benchmark | Memory Usage (kbytes) | |
|-----------|-----------------------|--------------|
| | Original | Instrumented |
| BH | 3 520 | 3 520 |
| Bisort | 3 008 | 3 040 |
| Health | 8 448 | 8 624 |
| MST | 4 752 | 6 272 |
| Perimeter | 6 064 | 6 528 |
| Power | 3 648 | 3 712 |
| Treeadd | 3 008 | 3 008 |
| TSP | 3 024 | 3 040 |

Possible Clients of the Analysis

Prefetching

Luk and Mowry - History-Pointer Prefetching [7]

Cahoon and McKinley - Jump-Pointer Prefetching [3]

```
struct myStruct{  
    int data;  
    struct myStruct *next;  
};
```



```
struct myStruct{  
    int data;  
    struct myStruct *next;  
    struct myStruct *prefetch;  
};
```

Possible Clients of the Analysis

Prefetching

In the first iteration through the pointer chasing loop there is no prefetching (initializing prefetch pointers).

If the traversal is known, the history pointers can be initialized as the data structure is allocated.

Eliminate compulsory cache misses

Possible Clients of the Analysis

Modify Data Layout

Memory Allocation

Calder *et al.* [4] and Chilimbi, Hill and Larus [6]

Create a custom allocator or a reallocation method that (re)organizes the data structure.

Manual & semi-automatic techniques.

Automatically insert the allocation calls with a *hint* from our analysis.

Possible Clients of the Analysis

Modify Data Layout

Structure Reorganization

Truong, Bodin and Seznec [8]

Chilimbi, Davidson and Larus [5]

Use analysis information with Chilimbi's data outlining or Truong's *ialloc* memory allocator to improve spatial locality.

Conclusion

Developed an efficient analysis to *automatically* determine the orientation of tree traversals.

Instrumented applications only require 7% more memory.

There are many clients for this analysis that can potentially improve program performance.

Questions?

References

- [1] J. Patterson. Modern Microprocessors A 90 Minute Guide!
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- [5] T.M. Chilimbi, B. Davidson and J.R. Larus. Cache-conscious structure definition. PLDI '99
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